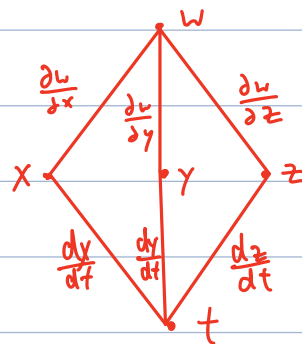


MATH 2010E TUTOR

Chain Rule: One Independent Variable

In Exercises 1–6, (a) express dw/dt as a function of t , both by using the Chain Rule and by expressing w in terms of t and differentiating directly with respect to t . Then (b) evaluate dw/dt at the given value of t .

6. $w = z - \sin xy$, $x = t$, $y = \ln t$, $z = e^{t-1}$; $t = 1$



Ans: a) $\frac{\partial w}{\partial x} = -y \cos(xy)$, $\frac{\partial w}{\partial y} = -x \cos(xy)$, $\frac{\partial w}{\partial z} = 1$
 $\frac{dx}{dt} = 1$, $\frac{dy}{dt} = \frac{1}{t}$, $\frac{dz}{dt} = e^{t-1}$

By chain rule,

$$\begin{aligned} \frac{dw}{dt} &= \frac{\partial w}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial w}{\partial y} \cdot \frac{dy}{dt} + \frac{\partial w}{\partial z} \cdot \frac{dz}{dt} \\ &= -(\ln t) \cos(t \ln t) \cdot 1 - t \cos(t \ln t) \cdot \frac{1}{t} + 1 \cdot e^{t-1} \\ &= -(\ln t + 1) \cos(t \ln t) + e^{t-1} \end{aligned}$$

OTOH, $w = e^{t-1} - \sin(t \ln t)$

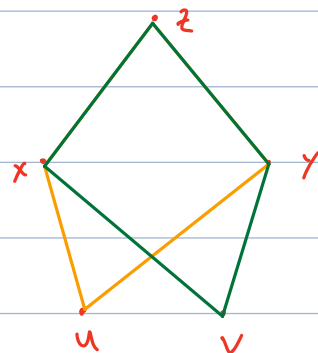
$$\begin{aligned} \Rightarrow \frac{dw}{dt} &= e^{t-1} - \cos(t \ln t) (\ln t + t \cdot \frac{1}{t}) \\ &= e^{t-1} - \cos(t \ln t) (\ln t + 1) \end{aligned}$$

b) $\left. \frac{dw}{dt} \right|_{t=1} = -(0 + 1) \cos(1 \cdot 0) + e^0$
 $= -1 + 1$
 $= 0$

Chain Rule: Two and Three Independent Variables

In Exercises 7 and 8, (a) express $\partial z/\partial u$ and $\partial z/\partial v$ as functions of u and v both by using the Chain Rule and by expressing z directly in terms of u and v before differentiating. Then (b) evaluate $\partial z/\partial u$ and $\partial z/\partial v$ at the given point (u, v) .

7. $z = 4e^x \ln y$, $x = \ln(u \cos v)$, $y = u \sin v$;
 $(u, v) = (2, \pi/4)$



Ans: a) By chain rule,

$$\begin{cases} \frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial u} \\ \frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial v} \end{cases}$$

$$\text{or } \begin{pmatrix} \frac{\partial z}{\partial u} \\ \frac{\partial z}{\partial v} \end{pmatrix} = \begin{pmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix}$$

$$= (4e^x \ln y \quad 4e^x/y) \begin{pmatrix} 1/u & -\tan v \\ \sin v & u \cos v \end{pmatrix}$$

$x = \ln(u \cos v)$
 $y = u \sin v$

$$= (4u \cos v \ln(u \sin v) \quad 4 \cot v) \begin{pmatrix} 1/u & -\tan v \\ \sin v & u \cos v \end{pmatrix}$$

OTOH,

$$\begin{aligned} z(u, v) &= 4 \exp(\ln(u \cos v)) \ln(u \sin v) \\ &= 4u \cos v \cdot \ln(u \sin v) \end{aligned}$$

$$\Rightarrow \frac{\partial z}{\partial u} = 4 \cos v \ln(u \sin v) + 4u \cos v \cdot \frac{\sin v}{u \sin v}$$
$$= 4 \cos v \ln(u \sin v) + 4 \cos v$$

$$\frac{\partial z}{\partial v} = -4u \sin v \cdot \ln(u \sin v) + 4u \cos v \cdot \frac{u \cos v}{u \sin v}$$
$$= -4u \sin v \ln(u \sin v) + 4u \cos v \cdot \cot v$$

b) At $(2, \pi/4)$, $\frac{\partial z}{\partial u} = \frac{4}{\sqrt{2}} \ln(\sqrt{2}) + \frac{4}{\sqrt{2}} = \sqrt{2} (\ln 2 + 2)$

$$\frac{\partial z}{\partial v} = -4(\sqrt{2}) \ln \sqrt{2} + 4(\sqrt{2}) \cdot 1 = -2\sqrt{2} \ln 2 + 4\sqrt{2}$$

In Exercises 11 and 12, (a) express $\partial u/\partial x$, $\partial u/\partial y$, and $\partial u/\partial z$ as functions of x , y , and z both by using the Chain Rule and by expressing u directly in terms of x , y , and z before differentiating. Then (b) evaluate $\partial u/\partial x$, $\partial u/\partial y$, and $\partial u/\partial z$ at the given point (x, y, z) .

11. $u = \frac{p - q}{q - r}$, $p = x + y + z$, $q = x - y + z$,
 $r = x + y - z$; $(x, y, z) = (\sqrt{3}, 2, 1)$

Ans: a) $\left(\frac{\partial u}{\partial p} \quad \frac{\partial u}{\partial q} \quad \frac{\partial u}{\partial r} \right) = \left(\frac{1}{q-r} \quad \frac{r-p}{(q-r)^2} \quad \frac{p-q}{(q-r)^2} \right)$

$$\begin{pmatrix} \frac{\partial p}{\partial x} & \frac{\partial p}{\partial y} & \frac{\partial p}{\partial z} \\ \frac{\partial q}{\partial x} & \frac{\partial q}{\partial y} & \frac{\partial q}{\partial z} \\ \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} & \frac{\partial r}{\partial z} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix}$$

By chain rule,

$$\begin{aligned} \left(\frac{\partial u}{\partial x} \quad \frac{\partial u}{\partial y} \quad \frac{\partial u}{\partial z} \right) &= \frac{1}{(q-r)^2} \begin{pmatrix} q-r & r-p & p-q \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix} \\ &= \frac{1}{(q-r)^2} \begin{pmatrix} 0 & 2p-2r & 2q-2p \end{pmatrix} \\ &= \frac{1}{(2z-2y)^2} \begin{pmatrix} 0 & 4z & -4y \end{pmatrix} \\ &= \frac{1}{(z-y)^2} \begin{pmatrix} 0 & z & -y \end{pmatrix} \end{aligned}$$

OTOH, $u = \frac{p-q}{q-r} = \frac{2y}{2z-2y} = \frac{y}{z-y}$

$\Rightarrow \frac{\partial u}{\partial x} = 0$

$\frac{\partial u}{\partial y} = \frac{1}{(z-y)^2} \left((z-y) - y(-1) \right) = \frac{z}{(z-y)^2}$

$\frac{\partial u}{\partial z} = -\frac{y}{(z-y)^2}$

b) At $(x, y, z) = (\sqrt{3}, 2, 1)$,

$\frac{\partial u}{\partial x} = 0$, $\frac{\partial u}{\partial y} = 1$, $\frac{\partial u}{\partial z} = -2$

40. Assume that $w = f\left(ts^2, \frac{s}{t}\right)$, $\frac{\partial f}{\partial x}(x, y) = xy$, and $\frac{\partial f}{\partial y}(x, y) = \frac{x^2}{2}$.

Find $\frac{\partial w}{\partial t}$ and $\frac{\partial w}{\partial s}$.

Ans: Let $x = ts^2$, $y = \frac{s}{t}$

Then $\frac{\partial x}{\partial t} = s^2$, $\frac{\partial x}{\partial s} = 2ts$, $\frac{\partial y}{\partial t} = -\frac{s}{t^2}$, $\frac{\partial y}{\partial s} = \frac{1}{t}$

By chain rule,

$$\left(\frac{\partial w}{\partial t} \quad \frac{\partial w}{\partial s}\right) = \left(\frac{\partial w}{\partial x} \quad \frac{\partial w}{\partial y}\right) \begin{pmatrix} \frac{\partial x}{\partial t} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial t} & \frac{\partial y}{\partial s} \end{pmatrix}$$

$$= \left(\frac{\partial f}{\partial x} \quad \frac{\partial f}{\partial y}\right) \begin{pmatrix} \frac{\partial x}{\partial t} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial t} & \frac{\partial y}{\partial s} \end{pmatrix}$$

$$= \left(ts^2 \cdot \frac{s}{t} \quad \frac{1}{2}(ts)^2\right) \begin{pmatrix} s^2 & 2ts \\ -\frac{s}{t^2} & \frac{1}{t} \end{pmatrix}$$

$$= \left(s^5 - \frac{1}{2}s^5 \quad 2ts^4 + \frac{1}{2}ts^4\right)$$

$$= \left(\frac{1}{2}s^5 \quad \frac{5}{2}ts^4\right)$$

=

44. Polar coordinates Suppose that we substitute polar coordinates $x = r \cos \theta$ and $y = r \sin \theta$ in a differentiable function $w = f(x, y)$.

a. Show that

$$\frac{\partial w}{\partial r} = f_x \cos \theta + f_y \sin \theta$$

and

$$\frac{1}{r} \frac{\partial w}{\partial \theta} = -f_x \sin \theta + f_y \cos \theta.$$

b. Solve the equations in part (a) to express f_x and f_y in terms of $\partial w / \partial r$ and $\partial w / \partial \theta$.

c. Show that

$$(f_x)^2 + (f_y)^2 = \left(\frac{\partial w}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial w}{\partial \theta}\right)^2.$$

Ans: a) By chain rule,

$$\frac{\partial w}{\partial r} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial r} = f_x \cos \theta + f_y \sin \theta$$

$$\frac{\partial w}{\partial \theta} = \frac{\partial w}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial w}{\partial y} \cdot \frac{\partial y}{\partial \theta} = f_x (-r \sin \theta) + f_y (r \cos \theta)$$

$$b) \begin{pmatrix} \frac{\partial w}{\partial r} \\ \frac{1}{r} \frac{\partial w}{\partial \theta} \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} f_x \\ f_y \end{pmatrix}$$

$$\begin{aligned} \text{So } \begin{pmatrix} f_x \\ f_y \end{pmatrix} &= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}^{-1} \begin{pmatrix} \frac{\partial w}{\partial r} \\ \frac{1}{r} \frac{\partial w}{\partial \theta} \end{pmatrix} \\ &= \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \frac{\partial w}{\partial r} \\ \frac{1}{r} \frac{\partial w}{\partial \theta} \end{pmatrix} \\ &= \begin{pmatrix} \frac{\partial w}{\partial r} \cos \theta - \frac{1}{r} \frac{\partial w}{\partial \theta} \sin \theta \\ \frac{\partial w}{\partial r} \sin \theta + \frac{1}{r} \frac{\partial w}{\partial \theta} \cos \theta \end{pmatrix} \end{aligned}$$

$$\begin{aligned} c) (f_x)^2 + (f_y)^2 &= \left(\frac{\partial w}{\partial r} \cos \theta - \frac{1}{r} \frac{\partial w}{\partial \theta} \sin \theta \right)^2 + \left(\frac{\partial w}{\partial r} \sin \theta + \frac{1}{r} \frac{\partial w}{\partial \theta} \cos \theta \right)^2 \\ &= \left(\frac{\partial w}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial w}{\partial \theta}\right)^2 + 0 \end{aligned}$$

Differentiating Integrals Under mild continuity restrictions, it is true that if

$$F(x) = \int_a^b g(t, x) dt,$$

(*) then $F'(x) = \int_a^b g_x(t, x) dt$. Using this fact and the Chain Rule, we can find the derivative of

$$F(x) = \int_a^{f(x)} g(t, x) dt$$

by letting

$$G(u, x) = \int_a^u g(t, x) dt, \quad \Rightarrow \quad \begin{cases} \frac{\partial G}{\partial u} = g(u, x) & \text{by FTC} \\ \frac{\partial G}{\partial x} = \int_a^u g_x(t, x) dt & \text{by (*)} \end{cases}$$

where $u = f(x)$. Find the derivatives of the functions in Exercises 51 and 52.

51. $F(x) = \int_0^{x^2} \sqrt{t^4 + x^3} dt$ 52. $F(x) = \int_{x^2}^1 \sqrt{t^3 + x^2} dt$

Ans: By chain rule,

$$\begin{aligned} \frac{dG}{dx} &= \frac{\partial G}{\partial u} \cdot \frac{du}{dx} + \frac{\partial G}{\partial x} \cdot \frac{dx}{dx} \\ &= g(u, x) \cdot \frac{du}{dx} + \int_a^u g_x(t, x) dt \end{aligned}$$

51) $g(t, x) = \sqrt{t^4 + x^3}$, $u = f(x) = x^2$

$$\begin{aligned} \int_0 \quad F'(x) &= \frac{d}{dx} G(f(x), x) = g(f(x), x) \cdot f'(x) + \int_0^{f(x)} g_x(t, x) dt \\ &= \sqrt{(x^2)^4 + x^3} \cdot (2x) + \int_0^{x^2} \frac{3x^2}{2\sqrt{t^4 + x^3}} dt \\ &= 2x\sqrt{x^8 + x^3} + \int_0^{x^2} \frac{3x^2}{2\sqrt{t^4 + x^3}} dt \end{aligned}$$